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OpenDoc/SOM and OLE/COM

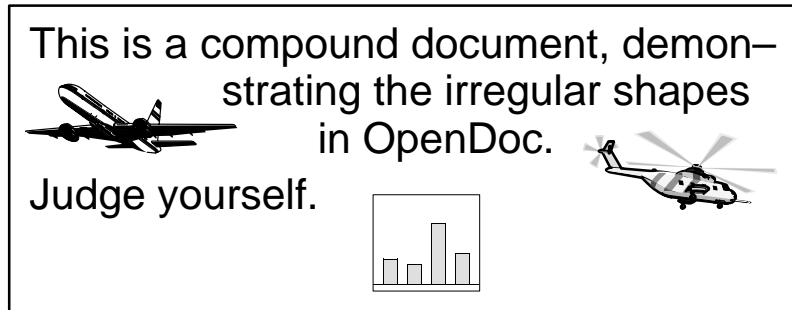
Berthold Reinwald

Purpose of the talk

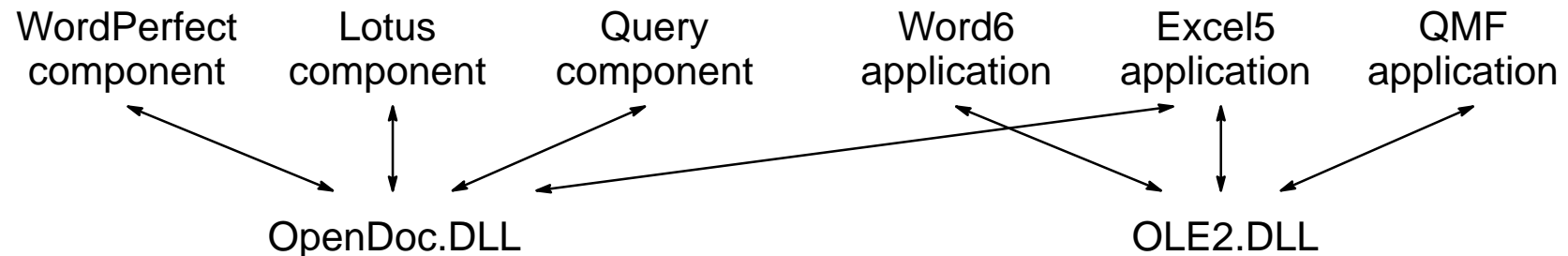
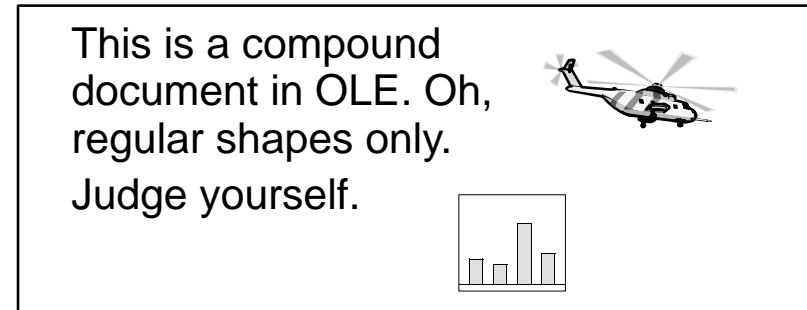
- ▶ Compound Documents: look & feel
- ▶ Component Software: what's behind the windows
- ▶ Technology Relationships: overview & preview
- ▶ OpenDoc/SOM and OLE/COM comparison
- ▶ Your first Component: “get down and dirty”
- ▶ Statement about the Applications

OpenDoc/OLE – Behind the Windows?

OpenDoc



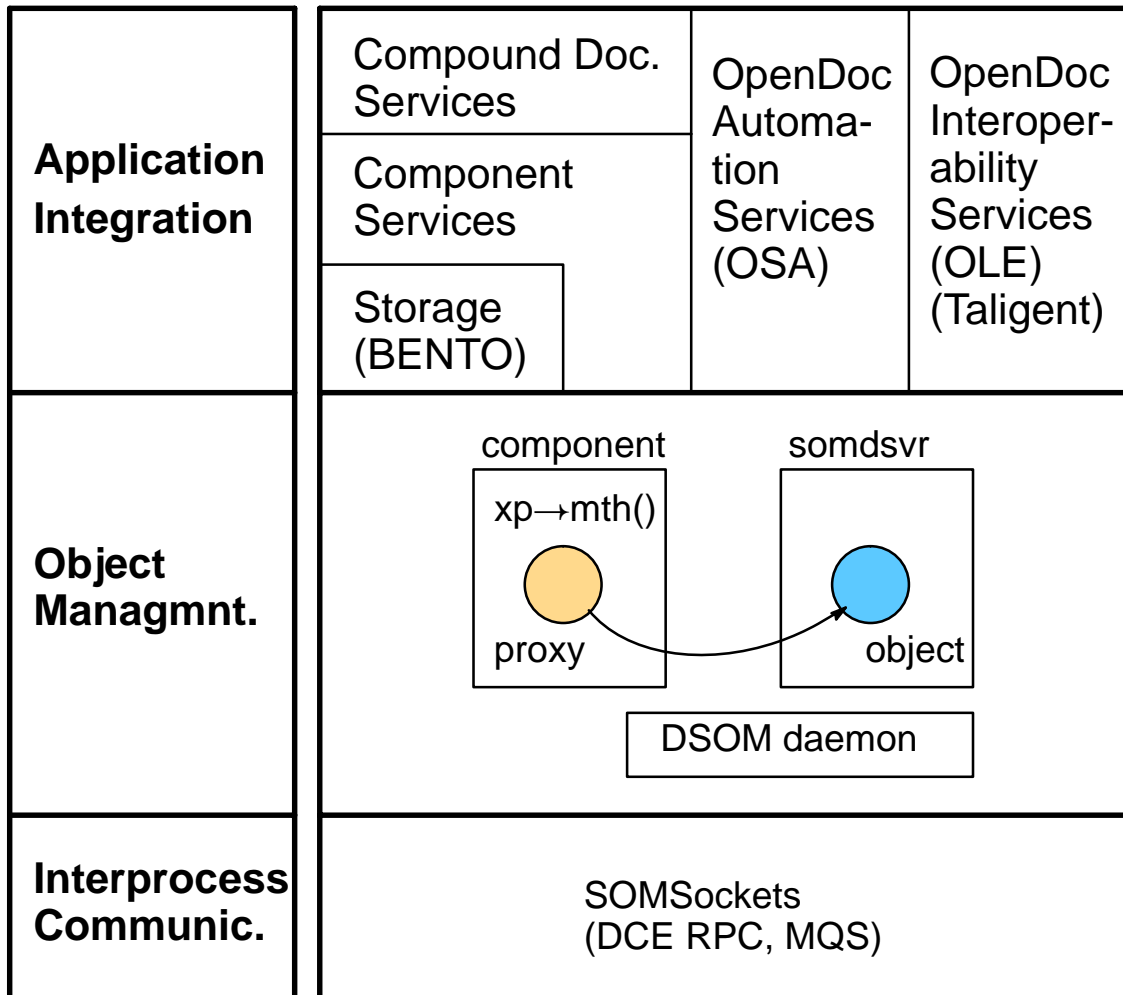
OLE



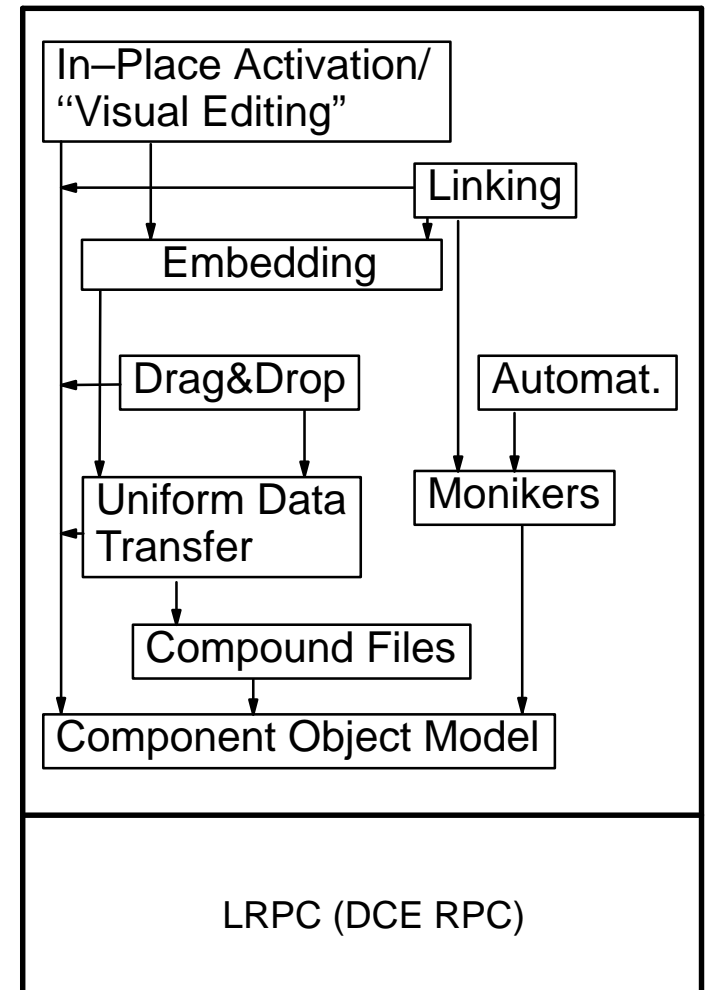
- ▶ a component/application is just a program executable or a DLL
- ▶ enabled software
- ▶ each component/application employs its own binary data (format)
- ▶ distributed objects
- ▶ remote method invocation

Technology Relationships

OpenDoc/SOM



OLE/COM



OpenDoc/SOM versus OLE/COM

	OpenDoc	OLE
Programming	SOM	COM
Development Effort	50 functions	126 functions
Scripting&Automat.	OSA, recordable macros	?
Activation Model	directly, across nested, multiple active objects	activate&edit, along nesting path, one at a time
Content Shape	irregularly	rectangular
Storage System	Bento	DocFiles (DOS FAT file)
Object Linking	persistent IDs	Moniker

	SOM	COM
Programming	object-oriented	object-based (no inherit.)
Languages	language-neutral (DTS)	language-neutral
Static Typing	statically typed	interfaces are static. typed
Distribution	DSOM	with Cairo
Method Resolution	offset, name, dispatch	interface vector table
Standards	OMG compliant (IDL, DTS)	MS proprietary
Platforms	OS/2, AIX, Windows	Windows, NT

Hello Component: HELLO.IDL

```
...
interface Hello : ContainerPart
{
    ...
    // # Instance data

    ODULong iteration;           // number of mouse double-clicks

    ODBoolean  fNeedToExternalize; // determine part changes
    ...
    // # identify SOM and OpenDoc methods that this class
    // # will re-implement

    Draw,           // draws part content in the provided facet
    Externalize,    // called when doc in which part resides is saved
    HandleEvent,    // process events, e.g. mouse clicks
    InitPart,       // called during instantiation of a part
    InitPartFromStorage // called during instantiation of a part from storage
        : override;

    ...
}
```

Hello Component: HELLO.CPP (1)

```
SOM_SCOPE void SOMLINK HelloInitPart (HelloPart *somSelf,
                                       Environment *ev,
                                       ODStorageUnit *storageUnit
                                       ) {

    HelloPartData *somThis = HelloPartGetData (somSelf);

    HelloPartMethodDebug ("HelloPart", "HelloInitPart");

    HelloPart_parent_ContainerPart_InitPart (somSelf, ev, storageUnit); // init parent

    // Initialize instance data, e.g. somThis->iteration = 0
    somSelf->HelloCommonInitPart(ev);

    // "set dirty"
    somThis->fNeedToExternalize = kODTrue;

    // prepare part for writing of data by adding a contents property value
    // to the storage unit
    storageUnit->AddProperty(ev, kODPropContents)->AddValue(ev, kHelloPart);

};
```

Hello Component: HELLO.CPP (2)

```
SOM_SCOPE void SOMLINK HelloExternalize (HelloPart *somSelf,
                                          Environment *ev )
{
    // Stores HelloPart part persistent data in part's storage unit
    ...
    // inherited info, e.g. mod date
    HelloPart_parent_ContainerPart_Externalize(somSelf, ev);

    if (somThis->fNeedToExternalize) {                                // check whether "dirty"

        ODStorageUnit *su = somSelf->GetStorageUnit(ev); // get ref to storage

        // focus on HelloPart storage unit
        su->Focus( ...)

        // write data to storage unit
        su->SetValue (ev, sizeof(SomThis->iteration), &somThis->iteration);

        // reset flag
        somThis->fNeedToExternalize = kODFalse;
    }
};
```


Hello Component: HELLO.CPP (3)

```
SOM_SCOPE void SOMLINK HelloInitPartFromStorage (
    HelloPart *somSelf,
    Environment *ev,
    ODStorageUnit *storageUnit // storage unit
)
{
    // retrieves the part's data from the storage
    ...
    // init parents
    HelloPart_parent_ContainerPart_InitPartFromStorage (somSelf, ev, storageUnit);

    // Init instance data of part, e.g. somThis->iteration = 0
    somSelf->HelloCommonInitPart(ev);

    somThis->fNeedToExternalize = kODFalse; // no need to externalize

    // focus storage unit on the part to be retrieved
    storageUnit->Focus (ev, ..., HelloPart, ...);

    // read the data from storage unit into the instance variable
    storageUnit->GetValue(ev, storageUnit->GetSize(ev), &somThis->iteration);
};
```